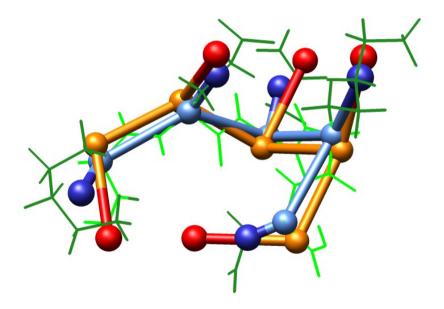
Constraint-based Lattice Model Refinement



Martin Mann and Alessandro Dal Palu.

Lattice model refinement of protein structures. ?, page 9, April 2010. Submitted. [COLAfit-src.tar.gz] [pdf] [bib]

Martin Mann, Rhodri Saunders, Cameron Smith, Rolf Backofen, and Charlotte Deane.

Latfit - producing high accuracy lattice models from protein atomic co-ordinates including side chains. ?, page 9, April 2010. Submitted. [pdf] [bib]

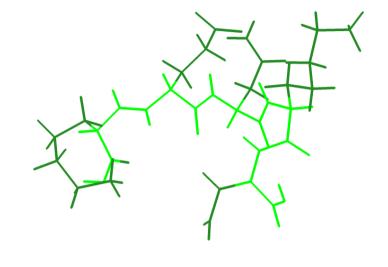
The Problem

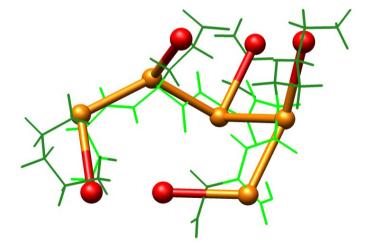
<u>Given:</u>

• Protein in full data (PDB)



 Lattice protein model with low deviation





(NP-complete in 3D-cubic for cRMSD optimization [Manuch&Gaur,2008])

Approaches

- Full enumeration [Covell&Jernigan,1990]
- Dynamic programming [Hinds&Levitt, 1992]
- Chain growth [Park&Levitt, 1995]
- Force field optimization [Reva et al., 1998]
- Simulated annealing [Ponty et al., 2008]
- Mainly heuristics ... biased results ?



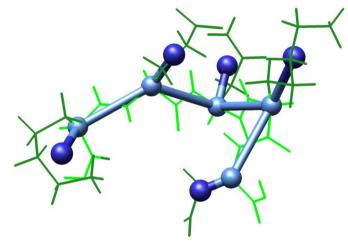
LatFit – our heuristics

- Chain growth algorithm
- Optimizes either
 - distance (d)RMSD or
 - coordinate (c)RMSD
- Open to backbone-only and side chain models
- Web interface available

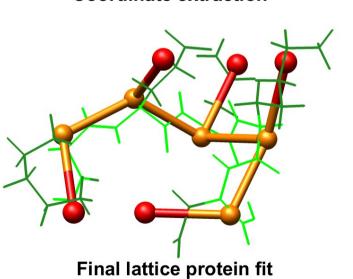
LatPack Tools - LatFit Result

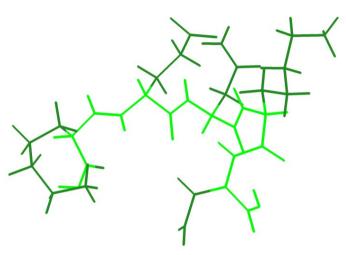
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HPconvert	Input Parameters				
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HEdeo	Chain Identifier Model Number	A 1			
degeneracy	Lattice Protein Type	Include Side-chains			
HEnnet	Lattice Form	FCC			
neutral network	CA-CA bond length	3.8 dRMSD			
HEdesign sec. design	Optimization Mode Max, to keep per Iteration	6HMSD 100			
LatFit	Output Format	PDB			
PDB to lattice	Output points to fit	yes			
Results	Output				
direct access	LatFit has produced a POB f	ite available for <u>download</u> . Click <u>here</u> to view the results.			
Help	The following distance measured	ures were obtained:			
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	dRMSD: 1.41052 Angs				
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		ing the CPSP-tools package with the following command and arguments: sigge000/CPSP_results/result/2010-03-18_13=14=45_JatFit_6969628.pdb*			
	-pdbAtom="CoM" -pdbChain="/	A" -pdbModel="1" -fitSideChain -lat="FCC" -bondLength="3.8" -opt="D"			
	-nKeep="100" -outMode="PDB	ourungData -v			
		Legal Disclosure and Contact			

LatFit - Workflow

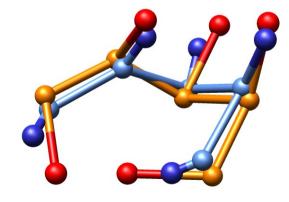


Coordinate extraction





Initial full atom model (PDB)



Best lattice fit calculation

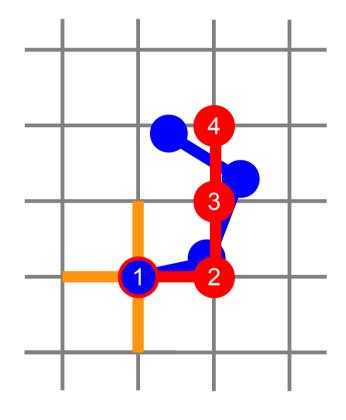
LatFit – cRMSD fitting procedure

For each Monomer:

- Generate all possible
 placements
- Select best
- Iterate until all placed

Problem:

 Once placed position is fixed



LatFit - Results

Backbone-only models

	Results taken from		Results taken from	LatFit	
	Park and Levitt [17]		Ponty $et \ al. \ [21]$	cRMSD optimisation	
	dRMSD	cRMSD	cRMSD	dRMSD	cRMSD
	μ	μ	μ (rescaled to \mathring{A})	μ / σ	μ / σ
cub	2.34	2.84	$3.5 \ (0.923 \cdot 3.8)$	2.042 / 0.228	2.539 / 0.234
fcc	1.46	1.78	-	$1.319 \ / \ 0.086$	$1.641 \ / \ 0.090$
210	1.02	1.24	-	$0.931 \ / \ 0.060$	$1.154 \ / \ 0.060$



Side chain models

		SD optimisation	LatFit - cRMSD optimisation		
	dRMSD	m cRMSD	dRMSD	m cRMSD	
	μ / σ	μ / σ	μ / σ	μ / σ	
cub	$2.779 \ / \ 0.754$	$4.157 \ / \ 1.331$	2.609 / 0.481	3.286 / 0.624	
fcc	$1.496 \ / \ 0.153$	$2.104 \ / \ 0.246$	$1.495 \ / \ 0.061$	$1.839 \ / \ 0.068$	
210	$1.126 \ / \ 0.068$	$1.601 \ / \ 0.100$	$1.185 \ / \ 0.042$	$1.450 \ / \ 0.047$	

Can we do better ?



Yes We Can !





Lattice Model Refinement

<u>Given:</u>

- Original protein
- Lattice model (LatFit)

<u>Goal:</u>

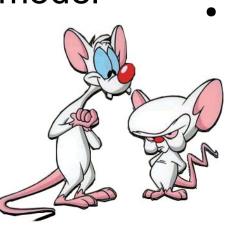
 Refined lattice model based on first model

<u>Idea:</u>

- Allow some relaxation
- Find best among these

<u>Method:</u>

- Constraint Programming
- Limited discrepancy search



Constraint Satisfaction Problem

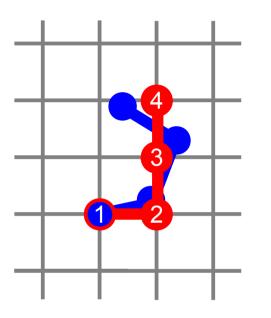
Definition

A Constraint Satisfaction Problem (CSP) consists of

- variables $\mathcal{X} = \{X_1, \ldots, X_n\}$,
- the domain D that associates finite domains $D_1 = D(X_1), \ldots, D_n = D(X_n)$ to \mathcal{X} .
- a set of constraints C.

A solution is an assignment of variables to values of their domains that satisfies the constraints.

Refinement CSP



 $\begin{array}{l} X = \{X_1, \ \dots, \ X_n\} \\ one \ for \ each \ monomer \end{array}$

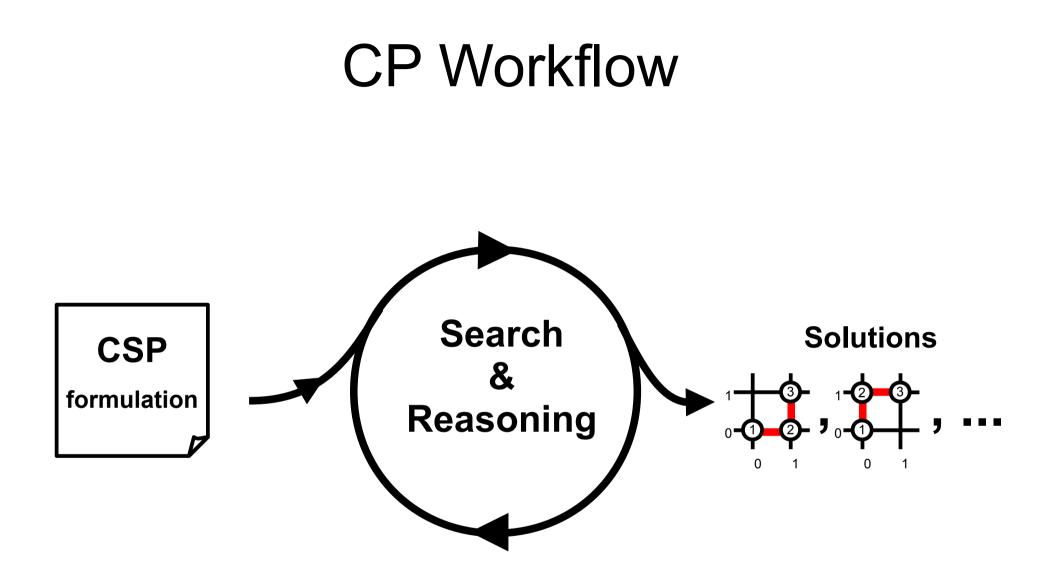
 $D(X_i) = \{ p : |p-M_i| \le d_{max} \}$ surrounding sphere

C₁ = SAW (X₁, ..., X_n) self avoiding walk

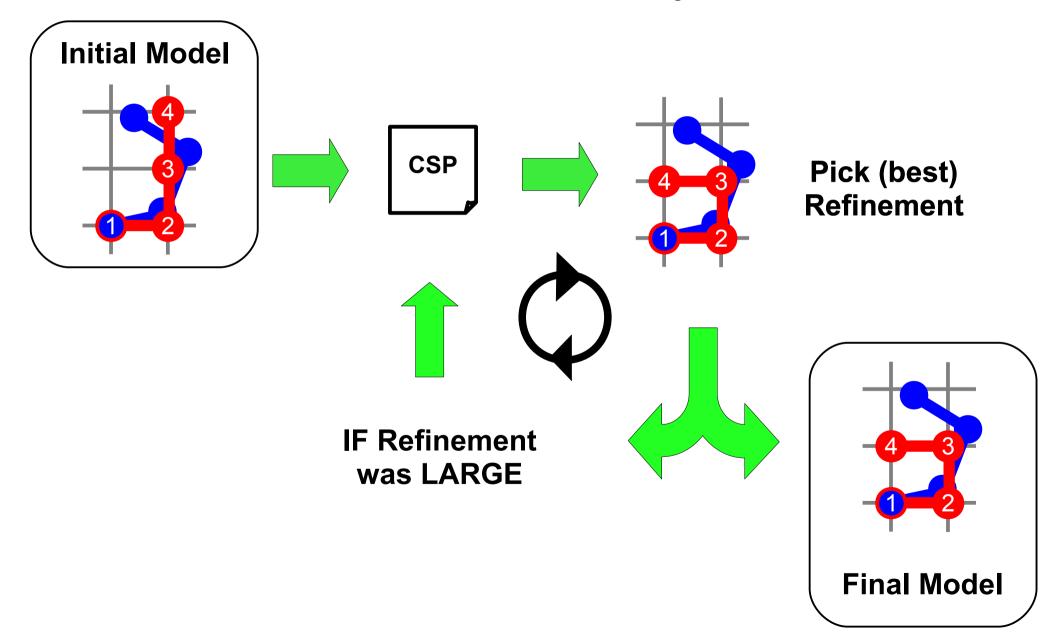
 $C_2 = |\{ i : X_i \neq M_i \}| \le \mathbf{K}$ *limited discrepancy*

Relaxation Parameters:

D _{max}	: maximal displacement
Κ	: number of replaced monomers



Local Search Cycle



Refinement - Results



dRMSD

		K			
8RX	Ν	1	2	3	4
	0	1.2469	1.2469	1.2469	1.2469
d	1	1.2319	1.2172	1.1639	1.1189
d_{\max}	2	1.2319	1.1674	1.1596	1.0884
	3	1.2319	1.1674	1.1596	1.0884
			ŀ	Υ Γ	
$1\mathrm{CK}$	A	1	2	3	4
	0	1.2370	1.2370	1.2370	1.2370
d	1	1.2226	1.2226	1.2226	1.2226
d_{\max}	2	1.2026	1.1887	1.1887	1.1887
	3	1.2026	1.1887	1.1887	1.1887
			ŀ	Υ Γ	
$2 \mathrm{FC}$	W	1	2	3	4
d_{\max}	0	1.1353	1.1353	1.1353	1.1353
	1	1.1353	1.1324	1.1317	1.1309
	2	1.1321	1.1300	1.1254	1.1200
	3	1.1321	1.1300	1.1254	1.1200

			1	K	
8RXN		1	2	3	4
	0	0.048	0.081	0.040	0.039
d	1	0.112	0.790	2.365	20.70
d_{\max}	2	0.068	0.983	6.500	106.6
	3	0.106	0.499	7.399	124.0
			1	K	
1CK	A	1	2	3	4
	0	0.031	0.030	0.027	0.037
d	1	0.402	0.615	3.442	39.27
d_{\max}	2	0.225	0.456	7.595	120.6
	3	0.421	0.616	8.573	140.2
			1	K	
2FCW		1	2	3	4
	0	0.043	0.050	0.058	0.078
d	1	0.118	1.997	49.99	1128
d_{\max}	2	0.294	7.192	341.8	14235
	3	0.332	8.129	394.5	16140

time in seconds

Refinement – Future Work

- Extension to side chain models
- Combination with local search
 - "local neighboring search" Gelato
 - Gradient walk
 - Simulated Annealing



Local move application

Any comments ?

